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9. The system as recited in claim 8, wherein said controller stops movement
5 of said moveable closure member in response to identification of said variation in said
defined field.

~~11.~~ The assembly as recited in claim ~~10~~, further comprising an actuator to move said window glass through said closure path.

13. The assembly as recited in claim 11, wherein said controller is in
25 communication with said actuator and said emitter, said controller operable to stop said
actuator in response to identification of said variation in said map.

sub a3

14. A method of detecting an object in a moveable closure path comprising the steps of:

(1) transmitting a signal within a defined field, said defined field adjacent a closure path of a moveable closure member;

5 (2) receiving said signal as transmitted within said defined field;

(3) mapping said signal received in said step (2); and

(4) identifying a variation in said mapped signal of said step (3).

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10 A method as recited in claim 14, further comprising the step of reversing movement of said moveable closure member in response to said variation in said signal.

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15 16. A method as recited in claim 14, wherein said step (1) includes transmitting said signal only when said moveable closure member is being closed.

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17. A method as recited in claim 14, wherein said step (1) includes transmitting said signal as a pulse.

add a4

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